The full π -calculus: simple and expressive

$\pi\text{-}\mathsf{Refresh.}$ What we know so far?

- We have studied the asynchronous monadic π -calculus
 - no continuation on the output (asynchronous) $\overline{u}\langle v\rangle$.*P*
 - only one value is communicated (monadic) $\overline{u}\langle v
 angle$

P,Q ::=	processes	
0	nil process	
$P \mid Q$	parallel composition of P and Q	
$(\nu a)P$	generation of a with scope P (also called restriction)	
!P	replication of P , i.e. infinite parallel composition $P P P \dots$	
$\overline{u}\langle v angle$	output of v on channel u	
u(x).P	input of <i>distinct</i> variables x on u , with continuation P	

$\pi\text{-calculus:}$ simple, but expressive

- Why expressive:
 - encoding data structures
 - encoding polyadic communication with monadic primitives
 - encoding synchronous communication with asynchronous (Honda/Tokoro, Boudol)
 - encoding choice (Nestmann, Palamidessi)
 - encoding recursion
 - encoding Higher order functions

Today you will learn how to master that expressiveness ... !!!

Synchronous π -calculus

- It is time to add continuation on output: $\overline{u} \langle v \rangle. {\it P}$
- We can define the synchronous calculus as follows:

 $\overline{a}\langle b\rangle.P\,|\,a(x).Q\longrightarrow P\,|\,Q\{^b/_x\}$



Q: Can we simulate synchronous communication with asynchronous? Hint: we need additional messages

Basic Encoding Definition

- $\llbracket P \rrbracket = Q$ is a function (mapping) from P to Q.
- A good mapping should be homomorphic.
- [[0]] = 0
- $\llbracket P \mid Q \rrbracket = \llbracket P \rrbracket \mid \llbracket Q \rrbracket$
- $[[(\nu a)P]] = (\nu a)[P]]$
- $[\![!P]\!] = ! [\![P]\!]$
 - Question:
- $[\![\overline{a}\langle b\rangle.P]\!]$ = some asynchronous π -term
- $\llbracket a(x).P \rrbracket$ = some asynchronous π -term

Synchronous π -calculus

SynchronousAsynchronous \Downarrow \Downarrow $\llbracket \overline{u} \langle v \rangle . P \rrbracket = (\nu c) (\overline{u} \langle c \rangle | c(y) . (\overline{y} \langle v \rangle | \llbracket P \rrbracket))$ where $\llbracket u(x) . P \rrbracket = u(y) . (\nu d) (\overline{y} \langle d \rangle | d(x) . \llbracket P \rrbracket)$ where

where $y \notin fv(P), c \notin fn(P)$ where $y \notin fv(P), d \notin fn(P)$

- Note: $\llbracket P \rrbracket$ represents the formal notation for the encoding of P
- Example:

$$\begin{split} \llbracket \overline{b} \langle e \rangle . P \rrbracket \mid \llbracket b(x) . Q \rrbracket & \longrightarrow \quad (\nu c) (c(y) . (\overline{y} \langle e \rangle \mid \llbracket P \rrbracket) \mid (\nu d) (\overline{c} \langle d \rangle \mid d(x) . \llbracket Q \rrbracket)) \\ & \longrightarrow \quad (\nu d) (\overline{d} \langle e \rangle \mid \llbracket P \rrbracket \mid d(x) . \llbracket Q \rrbracket) \longrightarrow \llbracket P \rrbracket \mid \llbracket Q \rrbracket \{ e/_X \} \end{split}$$

- How it works:
 - The channel \boldsymbol{u} is used to exchange a private name \boldsymbol{c}
 - The meaning of \boldsymbol{u} is that the receiver will be engaged in the rendez-vous with the sender
 - The sender confirms on \boldsymbol{c} by sending the private channel \boldsymbol{d}
 - Now the actual transmission can occur on the channel \boldsymbol{d}

Polyadic π -calculus

- Monadic channels carry exactly one name: $\overline{u}\langle v \rangle$, u(x)
- Polyadic channels carry a vector of names:

 $P ::= u(x_1, ..., x_n).P \qquad \text{input} \\ \overline{u} \langle v_1, ..., v_n \rangle.P \qquad \text{output}$

- We can communicate multiple values at the same time
- Reduction Rule:

$$\overline{a}\langle c_1,...,c_n\rangle.P \,|\, a(x_1,...,x_n).Q \longrightarrow P \,|\, Q\{\widetilde{c}/\widetilde{x}\}$$



Is there an encoding from polyadic to monadic channels?

Let's Try

• For every complex problem there is a simple solution ... that is wrong :)

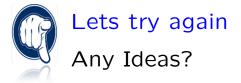
$$\begin{bmatrix} u(x_1, ..., x_n) . P \end{bmatrix} = u(x_1) . u(x_2) ... u(x_n) . \llbracket P \end{bmatrix}$$
$$\begin{bmatrix} \overline{u} \langle v_1, ..., v_n \rangle . P \end{bmatrix} = \overline{u} \langle v_1 \rangle . \overline{u} \langle v_2 \rangle ... \overline{u} \langle v_n \rangle . \llbracket P \end{bmatrix}$$

- Why the above encoding is ... wrong ?
- Hint: encode two processes in parallel sending on the same channel $[\![a(x_1, x_2).P_1 \,|\, a(x_3, x_4).P_2 \,|\, \overline{a} \langle c_1, c_2 \rangle.P_3]\!]$

Encoding Polyadic π -calculus

 $\begin{bmatrix} a(x_1, x_2) . P_1 \end{bmatrix} | \begin{bmatrix} a(x_3, x_4) . P_2 \end{bmatrix} | \begin{bmatrix} \overline{a} \langle c_1, c_2 \rangle . P_3 \end{bmatrix} =$ $a(x_1) . a(x_2) . \begin{bmatrix} P_1 \end{bmatrix} | a(x_3) . a(x_4) . \begin{bmatrix} P_2 \end{bmatrix} | \overline{a} \langle c_1 \rangle . \overline{a} \langle c_2 \rangle . \begin{bmatrix} P_3 \end{bmatrix} = R$

- This reduction is fine: $R \longrightarrow [\![P]\!] \{ {}^{c_1}/_{x_1}, {}^{c_2}/_{x_2} \} | a(x_3, x_4).[\![P_2]\!] | [\![P_3]\!]$
- But this is a mess: $R \longrightarrow a(x_2).[[P_1]] \{ {}^{c_1}/{x_1} \} | a(x_4).[[P_2]] \{ {}^{c_2}/{x_3} \} | [[P_3]]$



Another approach

- Use new binding
- We need private channel for each tuple

$$\begin{bmatrix} u(x_1, ..., x_n) . P \end{bmatrix} = u(z) . z(x_1) ... z(x_n) . \llbracket P \end{bmatrix}$$
$$\begin{bmatrix} \overline{u} \langle v_1, ..., v_n \rangle . P \end{bmatrix} = (\nu c) \overline{u} \langle c \rangle . \overline{c} \langle v_1 \rangle ... \overline{c} \langle v_n \rangle . \llbracket P \end{bmatrix}$$

- We still haven't finished? We need a condition ...

Let's put it all together

	Monadic	Polyadic
Asynchronous	$\overline{u}\langle v \rangle$ u(x).P	$ \bar{u} \langle v_1, \dots v_n \rangle \\ u(x_1, \dots x_n) . P_1 $
Synchronous	$\overline{u}\langle v\rangle.P$ u(x).P	$ \overline{u} \langle v_1, \dots v_n \rangle. P_1 u(x_1, \dots x_n). P_1 $

Adding more constructs ... Choice

In the asynchronous π -calculus there is no built-in choice operator +. Yet, we can represent *internal nondeterminism*.

$$P \oplus Q \stackrel{\text{df}}{=} (\nu a)(\overline{a} | a.P | a.Q) \text{ where } a \notin fn(P|Q)$$

There are two possible reductions:

- either $P \oplus Q \longrightarrow P \mid (\nu a)a.Q$
- or $P \oplus Q \longrightarrow (\nu a)a.P | Q$

Intuitively, since $(\nu a)a.Q$ and $(\nu a)a.P$ cannot reduce, the processes above are equivalent respectively to P and to Q.

Branching and Selection

• Structured external choice in the polyadic synchronous π -calculus:

 $P ::= \dots \mid u \rhd \{l_1 : P_1 [\cdots [l_n : P_n \} \mid u \triangleleft l.P$

- We have labels (ranged over l, l', ...)
- The branching waits for the selector to select a label
- The reduction is:

$$a \triangleright \{l_1 : P_1 [\cdots [l_n : P_n \} \mid a \triangleleft l_k . P \longrightarrow P_k \mid P \quad (1 \le k \le n)$$

Is there an encoding into the polyadic synchronous π -calculus

Branching and selection



The encoding of branching and selection into the polyadic synchronous π -calculus is defined as follows.

• $\llbracket 0 \rrbracket = 0$, $\llbracket P | Q \rrbracket = \llbracket P \rrbracket | \llbracket Q \rrbracket$, $\llbracket (\nu a) P \rrbracket = (\nu a) \llbracket P \rrbracket$, $\llbracket ! P \rrbracket = ! \llbracket P \rrbracket$,

•
$$\llbracket \overline{u}\langle \widetilde{v} \rangle \rrbracket = \overline{u}\langle \widetilde{v} \rangle$$
, $\llbracket u(\widetilde{x}).P \rrbracket = u(\widetilde{x}).\llbracket P \rrbracket$, and

ullet

 $\begin{bmatrix} u \triangleright \{l_1 : P_1 \ \| \ l_2 : P_2\} \end{bmatrix} = u(x) . (\nu c_1, c_2) (\overline{x} \langle c_1, c_2 \rangle | c_1. \llbracket P_1 \rrbracket | c_2. \llbracket P_2 \rrbracket)$ $\begin{bmatrix} u \triangleleft l_1.P \rrbracket = (\nu c) (\overline{u} \langle c \rangle | c(z_1, z_2). \overline{z_1}. \llbracket P \rrbracket) \\ \llbracket u \triangleleft l_2.P \rrbracket = (\nu c) (\overline{u} \langle c \rangle | c(z_1, z_2). \overline{z_2}. \llbracket P \rrbracket) \end{bmatrix}$

• We still haven't finished? We need a condition ...

Recursion

- We have
 - recursive definition $\mathbf{A}(\widetilde{x}) \stackrel{\mathsf{df}}{=} Q$
 - a process P which uses this definition, by calling $\mathbf{A}\langle \widetilde{v} \rangle$
- How to encode that behaviour in the asynchronous π -calculus ?
- Theorem to the rescue:
 - Theorem: Any process involving recursive denitions is representable using replication, and conversely replication is redundant in the presence of recursion.
 - Tricky: we also need restriction

Recursion vs Replication

Using replication and restriction we can encode recursive definitions. Suppose we have the recursive definition $\mathbf{A}(\tilde{x}) \stackrel{\text{df}}{=} Q$ and a process P which uses this definition, by calling $\mathbf{A}\langle \tilde{v} \rangle$. We can encode this behaviour in the asynchronous π -calculus as follows:

- 1. choose a fresh channel name a not occurring in P or Q;
- 2. let P_a and Q_a be P and Q, where each recursive call of the form $\mathbf{A}\langle \tilde{v} \rangle$ is replaced by an output process $\overline{a}\langle \tilde{v} \rangle$;
- 3. replace P by $(\nu a)(P_a | !a(\tilde{x}).Q_a)$

For example, consider the recursive definition and the reduction

$$\mathbf{BufferNext}(x) \stackrel{\mathsf{df}}{=} x(y).(\overline{x}\langle y \rangle | \mathbf{BufferNext}\langle y \rangle)$$
$$\overline{b}\langle c \rangle | \mathbf{BufferNext}\langle b \rangle \longrightarrow \overline{b}\langle c \rangle | \mathbf{BufferNext}\langle c \rangle$$

with their non-recursive version

$$\mathbf{BufferNext_a} \stackrel{\mathsf{df}}{=} x(y).(\overline{x}\langle y \rangle \,|\, \overline{a}\langle y \rangle)$$
$$(\nu \, a)(\overline{b}\langle c \rangle \,|\, \overline{a}\langle b \rangle \,|\, !a(x).\mathbf{BufferNext_a}) \stackrel{*}{\longrightarrow} (\nu \, a)(\overline{b}\langle c \rangle \,|\, \overline{a}\langle c \rangle \,|\, !a(x).\mathbf{BufferNext_a})$$