

# **Büchi Automata and Model Checking**

Yih-Kuen Tsay

Department of Information Management National Taiwan University

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### **Outline**



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### Introduction



- The simplest computation model for finite behaviors is the finite state automaton, which accepts finite words.
- The simplest computation model for infinite behaviors is the  $\omega$ -automaton, which accepts infinite words.
- Both have the same syntactic structure.
- Model checking traditionally deals with non-terminating systems.
- Infinite words conveniently represent the infinite behaviors exhibited by a non-terminating system.
- lacktriangle Büchi automata are the simplest kind of  $\omega$ -automata.
- They were first proposed and studied by J.R. Büchi in the early 1960's, to devise decision procedures for S1S.

### **Büchi Automata**



- A Büchi automaton (BA) has the same structure as a finite state automaton (FA) and is also given by a 5-tuple  $(\Sigma, Q, \Delta, q_0, F)$ :
  - **1**  $\Sigma$  is a finite set of symbols (the *alphabet*),
  - Q is a finite set of states,
  - **3**  $\Delta \subseteq Q \times \Sigma \times Q$  is the *transition relation*,
  - $q_0 \in Q$  is the *start* state (sometimes we allow multiple start states, indicated by  $Q_0$  or  $Q^0$ ), and
  - **5**  $F \subseteq Q$  is the set of *accepting* states.
- ♦ Let  $B = (\Sigma, Q, \Delta, q_0, F)$  be a BA and  $w = w_1 w_2 \dots w_i w_{i+1} \dots$  be an infinite string (or word) over  $\Sigma$ .
- A *run* of *B* over *w* is a sequence of states  $r_0, r_1, w_2, \ldots, r_i, r_{i+1}, \ldots$  such that
  - **1**  $r_0 = q_0$  and
  - **2**  $(r_i, w_{i+1}, r_{i+1}) \in \Delta$  for  $i \geq 0$ .

# Büchi Automata (cont.)



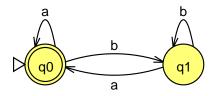
- Let  $inf(\rho)$  denote the set of states occurring infinitely many times in a run  $\rho$ .
- An infinite word  $w \in \Sigma^{\omega}$  is accepted by a BA B if there exists a run  $\rho$  of B over w satisfying the condition:

$$inf(\rho) \cap F \neq \emptyset$$
.

The *language* recognized by B (or the language of B), denoted L(B), is the set of all words that are accepted by B.

## An Example Büchi Automaton





- This Büchi automaton accepts infinite words over  $\{a, b\}$  that have infinitely many a's.
- Using an  $\omega$ -regular expression, its language is expressed as  $(b^*a)^{\omega}$ .

### **Closure Properties**



- A class of languages is closed under intersection if the intersection of any two languages in the class remains in the class.
- Analogously, for closure under complementation.

#### Theorem

The class of languages recognizable by Büchi automata is closed under **intersection** and **complementation** (and hence all boolean operations).

#### Proof.

Closure under intersection will be proven later by giving a procedure for constructing a Büchi automaton that recognizes the intersection of the languages of two given Büchi automata.

Closure under complementation will be proven in a separate

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### Generalized Büchi Automata



- A generalized Büchi automaton (GBA) has an acceptance component of the form  $F = \{F_1, F_2, \dots, F_n\} \subseteq 2^Q$ .
- GBA's naturally arise in the modeling of finite-state concurrent systems with fairness constraints.
- They are also a convenient intermediate representation in the translation from a linear temporal formula to an equivalent BA.
- There is a simple translation from a GBA to a Büchi automaton, as shown next.

### **GBA** to **BA**



- Let  $B = (\Sigma, Q, \Delta, Q^0, F)$ , where  $F = \{F_1, \dots, F_n\}$ , be a GBA.
- Construct  $B' = (\Sigma, Q \times \{0, \dots, n\}, \Delta', Q^0 \times \{0\}, Q \times \{n\}).$
- **?** The transition relation  $\Delta'$  is constructed such that  $(\langle q, x \rangle, a, \langle q', y \rangle) \in \Delta'$  when  $(q, a, q') \in \Delta$  and x and y are defined according to the following rules:
  - $\stackrel{*}{\circ}$  If  $q' \in F_i$  and x = i 1, then y = i.
  - N If x = n, then y = 0.
    - % Otherwise, y = x.
- $\bigcirc$  Claim: L(B') = L(B).

#### **Theorem**

For every GBA B, there is an equivalent BA B' such that L(B') = L(B).



## **Model Checking Using Automata**



- Kripke structures are the most commonly used model for concurrent and reactive systems in model checking.
- $\bigcirc$  Let AP be a set of atomic propositions.
- A Kripke structure M over AP is a four-tuple  $M = (S, R, S_0, L)$ :
  - **1** *S* is a finite set of states.
  - 2  $R \subseteq S \times S$  is a transition relation that must be total, that is, for every state  $s \in S$  there is a state  $s' \in S$  such that R(s, s').

  - **3**  $L: S \to 2^{AP}$  is a function that labels each state with the set of atomic propositions true in that state.

# Model Checking Using Automata (cont.)



- Finite automata can be used to model concurrent and reactive systems as well.
- One of the main advantages of using automata for model checking is that both the modeled system and the specification are represented in the same way.
- A Kripke structure directly corresponds to a Büchi automaton, where all the states are accepting.
- A Kripke structure (S, R, S<sub>0</sub>, L) can be transformed into an automaton A = (Σ, S ∪ {ι}, Δ, {ι}, S ∪ {ι}) with Σ = 2<sup>AP</sup> where
  - $\red (s, \alpha, s') \in \Delta$  for  $s, s' \in S$  iff  $(s, s') \in R$  and  $\alpha = L(s')$  and
  - $(\iota, \alpha, s) \in \Delta \text{ iff } s \in S_0 \text{ and } \alpha = L(s).$

# Model Checking Using Automata (cont.)



- The given system is modeled as a Büchi automaton A.
- Suppose the desired property is originally given by a linear temporal formula f.
- Let  $B_f$  (resp.  $B_{\neg f}$ ) denote a Büchi automaton equivalent to f (resp.  $\neg f$ ); we will later study how a temporal formula can be translated into an automaton.
- The model checking problem  $A \models f$  is equivalent to asking whether

$$L(A) \subseteq L(B_f)$$
 or  $L(A) \cap L(B_{\neg f}) = \emptyset$ .

- The well-used model checker SPIN, for example, adopts this automata-theoretic approach.
- So, we are left with two basic problems:
  - 🌻 Compute the intersection of two Büchi automata.
  - Test the emptiness of the resulting automaton.

### Intersection of Büchi Automata



- lacksquare Let  $B_1 = (\Sigma, Q_1, \Delta_1, Q_1^0, F_1)$  and  $B_2 = (\Sigma, Q_2, \Delta_2, Q_2^0, F_2)$ .
- $\P$  We can build an automaton for  $L(B_1) \cap L(B_2)$  as follows.
- $B_1 \cap B_2 = (\Sigma, Q_1 \times Q_2 \times \{0, 1, 2\}, \Delta, Q_1^0 \times Q_2^0 \times \{0\}, Q_1 \times Q_2 \times \{2\}).$
- We have  $(\langle r, q, x \rangle, a, \langle r', q', y \rangle) \in \Delta$  iff the following conditions hold:
  - $\red(r,a,r')\in\Delta_1 \text{ and } (q,a,q')\in\Delta_2.$
  - The third component is affected by the accepting conditions of B<sub>1</sub> and B<sub>2</sub>.
    - $\bullet$  If x=0 and  $r'\in F_1$ , then y=1.
    - $\bullet$  If x=1 and  $q'\in F_2$ , then y=2.
    - $\mathbf{\omega}$  If x = 2, then y = 0.
    - Otherwise, y = x.
- $\odot$  The third component is responsible for guaranteeing that accepting states from both  $B_1$  and  $B_2$  appear infinitely often.

# Intersection of Büchi Automata (cont.)



- A simpler intersection may be obtained when all of the states of one of the automata are accepting.
- Assuming all states of  $B_1$  are accepting and that the acceptance set of  $B_2$  is  $F_2$ , their intersection can be defined as follows:

$$B_1 \cap B_2 = (\Sigma, Q_1 \times Q_2, \Delta', Q_1^0 \times Q_2^0, Q_1 \times F_2)$$

where 
$$(\langle r, q \rangle, a, \langle r', q' \rangle) \in \Delta'$$
 iff  $(r, a, r') \in \Delta_1$  and  $(q, a, q') \in \Delta_2$ .

## **Checking Emptiness**



- Let  $\rho$  be an accepting run of a Büchi automaton  $B = (\Sigma, Q, \Delta, Q^0, F)$ .
- lacktriangle Then, ho contains infinitely many accepting states from F.
- Since Q is finite, there is some suffix  $\rho'$  of  $\rho$  such that every state on it appears infinitely many times.
- lacktriangle Each state on ho' is reachable from any other state on ho'.
- $\bullet$  Hence, the states in  $\rho'$  are included in a strongly connected component.
- This component is reachable from an initial state and contains an accepting state.

# **Checking Emptiness (cont.)**



- Conversely, any strongly connected component that is reachable from an initial state and contains an accepting state generates an accepting run of the automaton.
- $\bigcirc$  Thus, checking nonemptiness of L(B) is equivalent to finding a strongly connected component that is reachable from an initial state and contains an accepting state.
- That is, the language L(B) is nonempty iff there is a reachable accepting state with a cycle back to itself.

## **Double DFS Algorithm**



```
procedure emptiness for all q_0 \in Q^0 do dfs1(q_0); terminate(True); end procedure
```

```
procedure dfs1(q)

local q';

hash(q);

for all successors q' of q do

if q' not in the hash table then dfs1(q');

if accept(q) then dfs2(q);

end procedure
```

# Double DFS Algorithm (cont.)



```
procedure dfs2(q)

local q';

flag(q);

for all successors q' of q do

if q' on dfs1 stack then terminate(False);

else if q' not flagged then dfs2(q');

end if;

end procedure
```

#### Correctness



#### Lemma

Let q be a node that does not appear on any cycle. Then the DFS algorithm will backtrack from q only after all the nodes that are reachable from q have been explored and backtracked from.

#### **Theorem**

The double DFS algorithm returns a counterexample for the emptiness of the checked automaton B exactly when the language L(B) is not empty.

## **Correctness (cont.)**



- Suppose a second DFS is started from a state q and there is a path from q to some state p on the search stack of the first DFS.
- There are two cases:
  - There exists a path from q to a state on the search stack of the first DFS that contains only unflagged nodes when the second DFS is started from q.
  - On every path from q to a state on the search stack of the first DFS there exists a state r that is already flagged.
- The algorithm will find a cycle in the first case.
- We show that the second case is impossible.

## **Correctness (cont.)**



- Suppose the contrary: On every path from q to a state on the search stack of the first DFS there exists a state r that is already flagged.
- Then there is an accepting state from which a second DFS starts but fails to find a cycle even though one exists.
  - $\stackrel{\text{\tiny{\$}}}{\sim}$  Let q be the first such state.
  - Let r be the first flagged state that is reached from q during the second DFS and is on a cycle through q.
  - Let q' be the accepting state that starts the second DFS in which r was first encountered.
- $\odot$  Thus, according to our assumptions, a second DFS was started from q' before a second DFS was started from q.

## **Correctness (cont.)**



- Case 1: The state q' is reachable from q.
  - $ilde{ ilde{\#}}$  There is a cycle  $q' o \cdots o r o \cdots o q o \cdots o q'$ .
  - This cycle could not have been found previously.
  - $\circ$  This contradicts our assumption that q is the first accepting state from which the second DFS missed a cycle.
- **?** Case 2: The state q' is not reachable from q.
  - $ilde{*} \; q'$  cannot appear on a cycle.
  - $ilde{*} \; q$  is reachable from r and q' .
  - If q' does not occur on a cycle, by Lemma 23 we must have backtracked from q in the first DFS before from q'.
  - This contradicts our assumption about the order of doing the second DFS.

## **Concluding Remarks**



- Büchi automata occupy a very special position in logic and automata theory.
- They have found practical applications in linear temporal logic model checking.
- In another lecture, we will study how a linear temporal logic formula can be translated into an equivalent Büchi automaton.

#### References



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