

Logic

Part II: First-order Logic

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First-order Logic

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Motivation: First Order Logic

- in mathematics, we want to express propositions about individuals, e.g.

For every x we have $1 + x > x$

- in the example, the individuals are numbers, ranged over by the individual variable x
- we use constants (like 1) and functions (like $+$, arity 2) to construct *terms*
- relations (like $>$, arity 2) can be used to form *atomic propositions* about terms
- atomic propositions are used to construct more complex propositions
- first order logic (FOL) formalises such statements in an abstract setting

Principles of First Order Logic (FOL)

- first order logic formalises reasoning about statements that can refer to individuals through *individual variables*
- a fixed set of function symbols acts on the individuals
- a fixed set of relation symbols expresses predicates on the individuals
- more complex statements can be formed by connectives like $\wedge, \vee, \rightarrow, \neg$ and the quantifiers \forall, \exists
- first order logic is sufficient to formalise great parts of mathematics, for example arithmetic

The Language of FOL

- a first order *signature* $\Sigma = \langle \mathbf{F}, \mathcal{R} \rangle$ describes a language with
 - *function letters* $f \in \mathbf{F}$ with arity $\alpha(f) \in \mathbb{N}$
 - *relation letters* $r \in \mathcal{R}$ with arity $\alpha(r) \in \mathbb{N}$
- terms $\mathbf{T}(\Sigma, \mathcal{V})$ over Σ and a set \mathcal{V} of *individual variables* are inductively defined:
 - $\mathcal{V} \subseteq \mathbf{T}(\Sigma, \mathcal{V})$
 - for $f \in \mathbf{F}$ of arity n , $t_1, \dots, t_n \in \mathbf{T}(\Sigma, \mathcal{V})$, also $f(t_1, \dots, t_n) \in \mathbf{T}(\Sigma, \mathcal{V})$
- for a 0-ary constant d , we write $d()$ simply as d

Example

Signature $\Sigma_{\text{ar}} = \langle \mathbf{F}_{\text{ar}}, \mathcal{R}_{\text{ar}} \rangle$ of arithmetic:

- $\mathbf{F}_{\text{ar}} = \{\mathbf{0}, s, +, \times\}$, where $\alpha(\mathbf{0}) = 0$, $\alpha(s) = 1$,
 $\alpha(+)$ = $\alpha(\times) = 2$
- $\mathcal{R}_{\text{ar}} = \{\leq\}$, where $\alpha(\leq) = 2$
- examples for terms from $\mathbb{T}(\Sigma_{\text{ar}}, \{x, y\})$:
 $\mathbf{0}$, $s(\mathbf{0})$, $s(s(\mathbf{0}))$, \dots , $s(x)$, $\times(s(x), y)$, $s(\times(x, y))$, \dots
- but not $\mathbf{0}(\mathbf{0})$ or $\times(s(\mathbf{0}))$
- $\times(x, y)$ usually written $x \times y$, but still $\times(x, y) \equiv x \times y$

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The Language of FOL (II)

- an *atom* is either
 - of the form $r(t_1, \dots, t_n)$, where $r \in \mathcal{R}$, $\alpha(r) = n$, $t_1, \dots, t_n \in \mathbb{T}(\Sigma, \mathcal{V})$
 - or of the form $s \doteq t$, where $s, t \in \mathbb{T}(\Sigma, \mathcal{V})$
- we write r for $r()$ if $\alpha(r) = 0$
- the language of formulas of first-order logic over Σ and \mathcal{V} is given by the following grammar:

$$\varphi ::= \mathcal{A}(\Sigma, \mathcal{V}) \mid \perp \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \varphi \rightarrow \varphi \mid \forall \mathcal{V}. \varphi \mid \exists \mathcal{V}. \varphi$$

where $\mathcal{A}(\Sigma, \mathcal{V})$ are the atoms over Σ and \mathcal{V}

- \forall and \exists have the lowest precedence

Example

Atoms over Σ_{ar} and $\mathcal{V} = \{x, y, d, d'\}$:

- $x \doteq y$
- $x + y \doteq y + x$
- $s(s(\mathbf{0})) \times x \leq x + x$

Non-atomic formulas:

- $\neg(x \doteq s(x))$
- $(\exists d. x + d \doteq y) \rightarrow (\exists d'. s(x) + d' \doteq y) \vee s(x) \doteq y$
- $\forall x. x + x \leq x \times x$

Intuitive Semantics of the Quantifiers

- $\forall x.\varphi$ should be understood as “for all values of x , φ holds”
- $\exists x.\varphi$ should be understood as “there is a value of x such that φ holds”
- so the formula

$$\forall x.x \doteq \mathbf{0} \vee \exists y.x \doteq s(y)$$

could be understood as

every x is either equal to zero, or there exists a number y such that x is its successor

- **however**, this interpretation relies on an intuitive interpretation of the function symbols s and $\mathbf{0}$ and the relation symbol \doteq ; it is certainly not true for all interpretations of these symbols!

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Free and Bound Variables

- an appearance of an individual variable is called *bound* if it is within the scope of a quantifier, otherwise it is *free*
e.g. (free variables are red):

$$x \doteq s(y) \quad \exists x.x \doteq s(y) \quad \forall y.\exists x.x \doteq s(y)$$

- the same variable can appear both free and bound:

$$(\forall x.R(x, z) \rightarrow (\exists y.S(y, x))) \wedge T(x)$$

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The Set of Free Variables

- free variables in a term:
 1. $FV(x) = \{x\}$ for $x \in \mathcal{V}$
 2. $FV(f(t_1, \dots, t_n)) = \bigcup_{i \in \{1, \dots, n\}} FV(t_i)$
- free variables in a formula:
 1. $FV(r(t_1, \dots, t_n)) = \bigcup_{i \in \{1, \dots, n\}} FV(t_i)$
 2. $FV(s \doteq t) = FV(s) \cup FV(t)$
 3. $FV(\perp) = \emptyset$
 4. $FV(\varphi \wedge \psi) = FV(\varphi \vee \psi) = FV(\varphi \rightarrow \psi) = FV(\varphi) \cup FV(\psi)$
 5. $FV(\forall x. \varphi) = FV(\varphi) \setminus \{x\}$
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For example:

- $FV(x) = \{x\}$, $FV(0) = \emptyset$, $FV(s(y)) = \{y\}$
- $FV(x \doteq 0 \vee x \doteq s(y)) = \{x, y\}$
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Substitution in Terms and Formulas

- substituting a term t for a variable x in a term s ($s[t/x]$):

- $y[t/x] = \begin{cases} t & \text{if } x = y, \\ y & \text{otherwise} \end{cases}$

- $f(t_1, \dots, t_n)[t/x] = f(t_1[t/x], \dots, t_n[t/x])$

- on formulas, the definition is

- $r(t_1, \dots, t_n)[t/x] = r(t_1[t/x], \dots, t_n[t/x])$

- $(s_1 \doteq s_2)[t/x] = (s_1[t/x] \doteq s_2[t/x])$

- $\perp[t/x] = \perp$

- $(\varphi \circ \psi)[t/x] = (\varphi[t/x] \circ \psi[t/x])$, where \circ is either \wedge or \vee or \rightarrow

- $(\forall y. \varphi)[t/x] = \begin{cases} \forall y. \varphi & \text{if } x = y, \\ \forall y. (\varphi[t/x]) & \text{if } x \neq y, y \notin \text{FV}(t) \end{cases}$

$$(\exists y. \varphi)[t/x] = \begin{cases} \exists y. \varphi & \text{if } x = y, \\ \exists y. (\varphi[t/x]) & \text{if } x \neq y, y \notin \text{FV}(t) \end{cases}$$

Example

- $x[s(\mathbf{0})/x] \equiv s(\mathbf{0})$
- $y[s(\mathbf{0})/x] \equiv y$
- $(x \doteq \mathbf{0} \vee x \doteq s(y))[s(\mathbf{0})/x] \equiv s(\mathbf{0}) \doteq \mathbf{0} \vee s(\mathbf{0}) \doteq s(y)$
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- $(x \doteq \mathbf{0} \vee (\exists y.x \doteq s(y)))[s(y)/x]$ is not defined
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Alpha Equivalence

- $\forall x.\varphi$ *alpha reduces* to $\forall y.\varphi'$ if $\varphi' \equiv \varphi[y/x]$
 $\exists x.\varphi$ *alpha reduces* to $\exists y.\varphi'$ if $\varphi' \equiv \varphi[y/x]$
- φ is called *alpha equivalent* to ψ (written $\varphi \equiv_\alpha \psi$), if ψ results from φ by any number of alpha reductions on subformulas of φ
- Examples:
 - $(\forall x.R(x, x)) \equiv_\alpha (\forall y.R(y, y))$
 - $(\forall x.\exists x.S(x)) \equiv_\alpha (\forall y.\exists x.S(x)) \equiv_\alpha (\forall y.\exists z.S(z))$
 - $(\forall x.\exists y.T(x, y)) \not\equiv_\alpha (\forall x.\exists x.T(x, x))$

Notice that alpha reduction *never* changes the names of free variables.

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 - $(\forall x.\exists x.S(x)) \equiv_\alpha (\forall y.\exists x.S(x)) \equiv_\alpha (\forall y.\exists z.S(z))$
 - $(\forall x.\exists y.T(x, y)) \not\equiv_\alpha (\forall x.\exists x.T(x, x))$

Notice that alpha reduction *never* changes the names of free variables.

Alpha Equivalence

- $\forall x.\varphi$ *alpha reduces* to $\forall y.\varphi'$ if $\varphi' \equiv \varphi[y/x]$
 $\exists x.\varphi$ *alpha reduces* to $\exists y.\varphi'$ if $\varphi' \equiv \varphi[y/x]$
- φ is called *alpha equivalent* to ψ (written $\varphi \equiv_\alpha \psi$), if ψ results from φ by any number of alpha reductions on subformulas of φ
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Renaming Away

- we do not distinguish between alpha equivalent formulas
- hence, we can use alpha reduction to rename problematic bound variables such that substitution is always defined
- example:

$$(x \doteq \mathbf{0} \vee \exists y.x \doteq s(y))[s(y)/x]$$

is not defined, but

$$x \doteq \mathbf{0} \vee \exists y.x \doteq s(y) \equiv_{\alpha} x \doteq \mathbf{0} \vee \exists z.x \doteq s(z)$$

thus we can define

$$(x \doteq \mathbf{0} \vee \exists y.x \doteq s(y))[s(y)/x] := (x \doteq \mathbf{0} \vee \exists z.x \doteq s(z))[s(y)/x] \\ \equiv s(y) \doteq \mathbf{0} \vee \exists z.s(y) \doteq s(z)$$

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Motivation: Semantics of FOL

- the function and relation symbols in Σ have no predefined meaning
- thus, we do not know if $\forall x.x \doteq \mathbf{0}$ is true
- but some sentences are true no matter how the symbols are interpreted, e.g.:

$$(\forall x.\forall y.R(x, y) \rightarrow R(y, x)) \rightarrow R(a, b) \rightarrow R(b, a)$$

- how do we evaluate, e.g., $\forall x.\neg R(x, x)$?
 - we need to know what x can stand for, and for which of these values R is true
 - then we would like to evaluate $\neg R(x, x)$, where x is bound to any of its possible values
- thus, we need to consider not only the interpretation of the function and relation symbols, but also variable bindings

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Semantics: Structures, Interpretations and Assignments

- a (first order) structure $\mathcal{M} = \langle D, I \rangle$ for a signature Σ consists of
 - a non-empty set D , the *domain*
 - an interpretation $I = \langle \llbracket \cdot \rrbracket_{\mathcal{F}}, \llbracket \cdot \rrbracket_{\mathcal{R}} \rangle$ such that
 - for every $f \in \mathcal{F}$ with $\alpha(f) = n$, $\llbracket f \rrbracket_{\mathcal{F}}: D^n \rightarrow D$
 - for every $r \in \mathcal{R}$ with $\alpha(r) = n$, $\llbracket r \rrbracket_{\mathcal{R}}: D^n \rightarrow \mathcal{B}$
- a *variable assignment* on I is a function $\sigma: \mathcal{V} \rightarrow D$

We write $\sigma[x := t]$ for the assignment

$$y \mapsto \begin{cases} t & \text{if } x = y \\ \sigma(y) & \text{otherwise} \end{cases}$$

Semantics: Interpreting Terms and Formulas

- interpretation of terms over \mathcal{M} and σ :
 - $\llbracket x \rrbracket_{\mathcal{M},\sigma} := \sigma(x)$
 - $\llbracket f(t_1, \dots, t_n) \rrbracket_{\mathcal{M},\sigma} := \llbracket f \rrbracket_{\mathcal{F}}(\llbracket t_1 \rrbracket_{\mathcal{M},\sigma}, \dots, \llbracket t_n \rrbracket_{\mathcal{M},\sigma})$
- interpretation of formulas:
 - $\llbracket r(t_1, \dots, t_n) \rrbracket_{\mathcal{M},\sigma} := \llbracket r \rrbracket_{\mathcal{R}}(\llbracket t_1 \rrbracket_{\mathcal{M},\sigma}, \dots, \llbracket t_n \rrbracket_{\mathcal{M},\sigma})$
 - $\llbracket s \doteq t \rrbracket_{\mathcal{M},\sigma} := \mathbf{T}$ if $\llbracket s \rrbracket_{\mathcal{M},\sigma} = \llbracket t \rrbracket_{\mathcal{M},\sigma}$, otherwise
 $\llbracket s \doteq t \rrbracket_{\mathcal{M},\sigma} := \mathbf{F}$
 - $\llbracket \perp \rrbracket_{\mathcal{M},\sigma}, \llbracket \varphi \wedge \psi \rrbracket_{\mathcal{M},\sigma}$, etc.: as before
 - $\llbracket \forall x.\varphi \rrbracket_{\mathcal{M},\sigma} := \begin{cases} \mathbf{T} & \text{if, for all } d \in D, \llbracket \varphi \rrbracket_{\mathcal{M},\sigma[x:=d]} = \mathbf{T}, \\ \mathbf{F} & \text{otherwise} \end{cases}$
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Example

A structure $\mathcal{M} = \langle \mathbb{N}, \langle [\![\]\!]_{\mathcal{F}}, [\![\]\!]_{\mathcal{R}} \rangle \rangle$ for Σ_{ar}

- $[\![\mathbf{0}]\!]_{\mathcal{F}} = 0$
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- $\llbracket + \rrbracket_{\mathbf{F}}(m, n) = m + n$
- $\llbracket \times \rrbracket_{\mathbf{F}}(m, n) = m \times n$
- $\llbracket \leq \rrbracket_{\mathcal{R}}(m, n) = \begin{cases} \mathbf{T} & \text{if } m \leq n \\ \mathbf{F} & \text{otherwise} \end{cases}$

Consider $\sigma = \{x \mapsto 0, y \mapsto 1\}$, then

- $\llbracket x \rrbracket_{\mathcal{M}, \sigma} = 0$, $\llbracket y + y \rrbracket_{\mathcal{M}, \sigma} = 2$, $\llbracket \mathbf{0} \rrbracket_{\mathcal{M}, \sigma} = 0$, $\llbracket s(s(\mathbf{0})) \rrbracket_{\mathcal{M}, \sigma} = 2$,
 $\llbracket y \dot{=} s(s(\mathbf{0})) \rrbracket_{\mathcal{M}, \sigma} = \mathbf{F}$
- $\llbracket \perp \rrbracket_{\mathcal{M}, \sigma} = \mathbf{F}$, $\llbracket \neg(x \dot{=} y) \rrbracket_{\mathcal{M}, \sigma} = \mathbf{T}$
- $\llbracket x \leq y \rrbracket_{\mathcal{M}, \sigma} = \mathbf{T}$
- $\llbracket \exists x. \forall y. \neg(x \dot{=} y) \wedge x \leq y \rrbracket_{\mathcal{M}, \sigma} = \mathbf{F}$

Example

A structure $\mathcal{M} = \langle \mathbb{N}, \langle \llbracket \cdot \rrbracket_{\mathbf{F}}, \llbracket \cdot \rrbracket_{\mathcal{R}} \rangle \rangle$ for Σ_{ar}

- $\llbracket \mathbf{0} \rrbracket_{\mathbf{F}} = 0$
- $\llbracket s \rrbracket_{\mathbf{F}}(n) = n + 1$
- $\llbracket + \rrbracket_{\mathbf{F}}(m, n) = m + n$
- $\llbracket \times \rrbracket_{\mathbf{F}}(m, n) = m \times n$
- $\llbracket \leq \rrbracket_{\mathcal{R}}(m, n) = \begin{cases} \mathbf{T} & \text{if } m \leq n \\ \mathbf{F} & \text{otherwise} \end{cases}$

Consider $\sigma = \{x \mapsto 0, y \mapsto 1\}$, then

- $\llbracket x \rrbracket_{\mathcal{M}, \sigma} = 0, \llbracket y + y \rrbracket_{\mathcal{M}, \sigma} = 2, \llbracket \mathbf{0} \rrbracket_{\mathcal{M}, \sigma} = 0, \llbracket s(s(\mathbf{0})) \rrbracket_{\mathcal{M}, \sigma} = 2,$
 $\llbracket y \dot{=} s(s(\mathbf{0})) \rrbracket_{\mathcal{M}, \sigma} = \mathbf{F}$
- $\llbracket \perp \rrbracket_{\mathcal{M}, \sigma} = \mathbf{F}, \llbracket \neg(x \dot{=} y) \rrbracket_{\mathcal{M}, \sigma} = \mathbf{T}$
- $\llbracket x \leq y \rrbracket_{\mathcal{M}, \sigma} = \mathbf{T}$
- $\llbracket \exists x. \forall y. \neg(x \dot{=} y) \wedge x \leq y \rrbracket_{\mathcal{M}, \sigma} = \mathbf{F}$

Satisfiability and Validity

For a structure \mathcal{M} , an assignment σ , a formula φ and a set Γ of formulas, we define

- $\mathcal{M}, \sigma \models \varphi$: $\llbracket \varphi \rrbracket_{\mathcal{M}, \sigma} = \mathbf{T}$
- $\mathcal{M} \models \varphi$ (“ \mathcal{M} is a model for φ ”): $\mathcal{M}, \sigma \models \varphi$ for any σ
- $\varphi \Rightarrow \psi$: if $\mathcal{M}, \sigma \models \varphi$ then also $\mathcal{M}, \sigma \models \psi$
- $\models \varphi$ (“ φ is valid”): $\mathcal{M} \models \varphi$ for any structure \mathcal{M}
- $\mathcal{M}, \sigma \models \Gamma$: for all $\gamma \in \Gamma$ we have $\mathcal{M}, \sigma \models \gamma$
- $\Gamma \models \varphi$: for any \mathcal{M} and σ with $\mathcal{M}, \sigma \models \Gamma$ we also have $\mathcal{M}, \sigma \models \varphi$

Example: $\models \exists x.D(x) \rightarrow (\forall y.D(y))$ (“Drinker Paradox”)

Proof of $\models \exists x.D(x) \rightarrow (\forall y.D(y))$

Take the signature $\Sigma_D = \langle \emptyset, \{D\} \rangle$ with $\alpha(D) = 1$ and the set $\mathcal{V}_D = \{x, y\}$ of variables; the Drinker Paradox is clearly a formula over Σ_D and \mathcal{V}_D .

Proof of $\models \exists x.D(x) \rightarrow (\forall y.D(y))$

- $\Sigma_D = \langle \emptyset, \{D/1\} \rangle$, $\mathcal{V}_D = \{x, y\}$

Now assume we are given an arbitrary structure

$\mathcal{M} = \langle E, \langle \llbracket \cdot \rrbracket_{\mathcal{F}}, \llbracket \cdot \rrbracket_{\mathcal{R}} \rangle \rangle$ and a variable assignment $\sigma: \mathcal{V}_D \rightarrow E$. By our definition of semantics, E is a non-empty set; pick an element $e_0 \in E$.

Proof of $\models \exists x.D(x) \rightarrow (\forall y.D(y))$

- $\Sigma_D = \langle \emptyset, \{D/1\} \rangle$, $\mathcal{V}_D = \{x, y\}$
- structure \mathcal{M} , domain E , assignment σ ; choose $e_o \in E$

Proof of $\models \exists x.D(x) \rightarrow (\forall y.D(y))$

- $\Sigma_D = \langle \emptyset, \{D/1\} \rangle$, $\mathcal{V}_D = \{x, y\}$
- structure \mathcal{M} , domain E , assignment σ ; choose $e_o \in E$

Observe that $\llbracket D \rrbracket_{\mathcal{R}}$ is a function from E to \mathcal{B} , i.e. $\llbracket D \rrbracket_{\mathcal{R}}(e)$ is either T or F for every $e \in E$.

Proof of $\models \exists x.D(x) \rightarrow (\forall y.D(y))$

- $\Sigma_D = \langle \emptyset, \{D/1\} \rangle$, $\mathcal{V}_D = \{x, y\}$
- structure \mathcal{M} , domain E , assignment σ ; choose $e_o \in E$
- $\llbracket D \rrbracket_{\mathcal{R}}: E \rightarrow \mathcal{B}$

Proof of $\models \exists x.D(x) \rightarrow (\forall y.D(y))$

- $\Sigma_D = \langle \emptyset, \{D/1\} \rangle$, $\mathcal{V}_D = \{x, y\}$
- structure \mathcal{M} , domain E , assignment σ ; choose $e_o \in E$
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- We now distinguish two cases:

Proof of $\models \exists x.D(x) \rightarrow (\forall y.D(y))$

- $\Sigma_D = \langle \emptyset, \{D/1\} \rangle$, $\mathcal{V}_D = \{x, y\}$
- structure \mathcal{M} , domain E , assignment σ ; choose $e_o \in E$
- $\llbracket D \rrbracket_{\mathcal{R}}: E \rightarrow \mathcal{B}$
- We now distinguish two cases:
 - If $\llbracket D \rrbracket_{\mathcal{R}}(e) = \mathbf{T}$ for all $e \in E$, then

$$\llbracket D(y) \rrbracket_{\mathcal{M}, \sigma[x:=e_o][y:=e]} = \llbracket D \rrbracket_{\mathcal{R}}(e) = \mathbf{T}$$

for all $e \in E$, hence

$$\llbracket \forall y.D(y) \rrbracket_{\mathcal{M}, \sigma[x:=e_o]} = \mathbf{T}$$

Certainly also

$$\llbracket D(x) \rrbracket_{\mathcal{M}, \sigma[x:=e_o]} = \mathbf{T}$$

and thus

$$\llbracket D(x) \rightarrow (\forall y.D(y)) \rrbracket_{\mathcal{M}, \sigma[x:=e_o]} = \mathbf{T}$$

This shows that

$$\llbracket \exists x.D(x) \rightarrow (\forall y.D(y)) \rrbracket_{\mathcal{M}, \sigma} = \mathbf{T}.$$

Proof of $\models \exists x.D(x) \rightarrow (\forall y.D(y))$

- $\Sigma_D = \langle \emptyset, \{D/1\} \rangle$, $\mathcal{V}_D = \{x, y\}$
- structure \mathcal{M} , domain E , assignment σ ; choose $e_o \in E$
- $\llbracket D \rrbracket_{\mathcal{R}}: E \rightarrow \mathcal{B}$
- We now distinguish two cases:
 - $\llbracket D \rrbracket_{\mathcal{R}}(e) = \mathbf{T}$ for all e : $\llbracket \exists x.D(x) \rightarrow (\forall y.D(y)) \rrbracket_{\mathcal{M}, \sigma} = \mathbf{T}$.
 - Otherwise, $\llbracket D \rrbracket_{\mathcal{R}}(e_1)$ is \mathbf{F} for some e_1 , hence

$$\llbracket D(x) \rrbracket_{\mathcal{M}, \sigma[x:=e_1]} = \mathbf{F}$$

But then,

$$\llbracket D(x) \rightarrow (\forall y.D(y)) \rrbracket_{\mathcal{M}, \sigma[x:=e_1]} = \mathbf{T}$$

and consequently

$$\llbracket \exists x.D(x) \rightarrow (\forall y.D(y)) \rrbracket_{\mathcal{M}, \sigma} = \mathbf{T}.$$

Proof of $\models \exists x.D(x) \rightarrow (\forall y.D(y))$

- $\Sigma_D = \langle \emptyset, \{D/1\} \rangle$, $\mathcal{V}_D = \{x, y\}$
- structure \mathcal{M} , domain E , assignment σ ; choose $e_o \in E$
- $\llbracket D \rrbracket_{\mathcal{R}}: E \rightarrow \mathcal{B}$
- We now distinguish two cases:
 - $\llbracket D \rrbracket_{\mathcal{R}}(e) = \mathsf{T}$ for all e : $\llbracket \exists x.D(x) \rightarrow (\forall y.D(y)) \rrbracket_{\mathcal{M}, \sigma} = \mathsf{T}$.
 - Otherwise, too.

In conclusion, we have shown that $\models_{\mathcal{M}, \sigma} \exists x.D(x) \rightarrow (\forall y.D(y))$ for arbitrary \mathcal{M} and σ , thus establishing

$$\models \exists x.D(x) \rightarrow (\forall y.D(y)).$$

Basic Results

Fix some signature Σ and a set \mathcal{V} of variables.

Lemma (agreement lemma)

Let \mathcal{M} be a structure for Σ , φ a formula, and σ, σ' variable assignments such that $\sigma(x) = \sigma'(x)$ for all $x \in \text{FV}(\varphi)$. Then $\mathcal{M}, \sigma \models \varphi$ iff $\mathcal{M}, \sigma' \models \varphi$.

Corollary

The interpretation of a closed formula is independent of variable assignments.

Lemma (alpha equivalent formulas are semantically equivalent)

Alpha equivalent formulas evaluate to the same truth value.

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Corollary

The interpretation of a closed formula is independent of variable assignments.

Lemma (alpha equivalent formulas are semantically equivalent)

Alpha equivalent formulas evaluate to the same truth value.

Some Equivalences of FOL

- $(\forall x.\varphi) \Leftrightarrow \neg(\exists x.\neg\varphi)$
- $(\forall x.\varphi \wedge \psi) \Leftrightarrow (\forall x.\varphi) \wedge (\forall x.\psi)$
- $(\exists x.\varphi \vee \psi) \Leftrightarrow (\exists x.\varphi) \vee (\exists x.\psi)$
- $(\forall x.\forall y.\varphi) \Leftrightarrow (\forall y.\forall x.\varphi)$
- $(\exists x.\exists y.\varphi) \Leftrightarrow (\exists y.\exists x.\varphi)$
- $(\exists x.\forall y.\varphi) \rightarrow (\forall y.\exists x.\varphi)$, but *not vice versa*

Truth Tables for FOL?

- for $\varphi \in \text{PF}$, we can always find out whether $\models \varphi$ by drawing a truth table
- how about $\varphi \in \text{FOL}$?
 - we need to consider all possible structures
 - in particular, all possible domains, all possible functions over them
 - but domains could be infinite...
- unfortunate truth:

Theorem (Undecidability of First Order Logic)

Given an arbitrary first order formula φ , it is undecidable whether $\models \varphi$.

Sequent Calculus


相繼式演算

Principles of Sequent Calculus

- sequent: $\Gamma \vdash \Delta$
where Γ and Δ are finite sets of formulas
- intuitive meaning: if **every** formula in Γ is true, then **one** formula in Δ is true
- sequent calculus LK: system of derivation rules
- allows us to derive sequents that are correct according to the intuitive interpretation

Example Derivation

basic sequent


$$\begin{array}{l} (\wedge R) \frac{P, Q \vdash P \quad P, Q \vdash Q}{P, Q \vdash P \wedge Q} \\ (\neg R) \frac{P, Q \vdash P \wedge Q}{P \vdash P \wedge Q, \neg Q} \\ (\neg R) \frac{P \vdash P \wedge Q, \neg Q}{\vdash P \wedge Q, \neg P, \neg Q} \\ (\neg L) \frac{\vdash P \wedge Q, \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P, \neg Q} \\ (\vee R) \frac{\neg(P \wedge Q) \vdash \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P \vee \neg Q} \end{array}$$

Example Derivation

basic sequent

$$\begin{array}{c} (\wedge R) \frac{P, Q \vdash P \quad P, Q \vdash Q}{P, Q \vdash P \wedge Q} \\ (\neg R) \frac{P, Q \vdash P \wedge Q}{P \vdash P \wedge Q, \neg Q} \\ (\neg R) \frac{P \vdash P \wedge Q, \neg Q}{\vdash P \wedge Q, \neg P, \neg Q} \\ (\neg L) \frac{\vdash P \wedge Q, \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P, \neg Q} \\ (\vee R) \frac{\neg(P \wedge Q) \vdash \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P \vee \neg Q} \end{array}$$

derivation step

Example Derivation

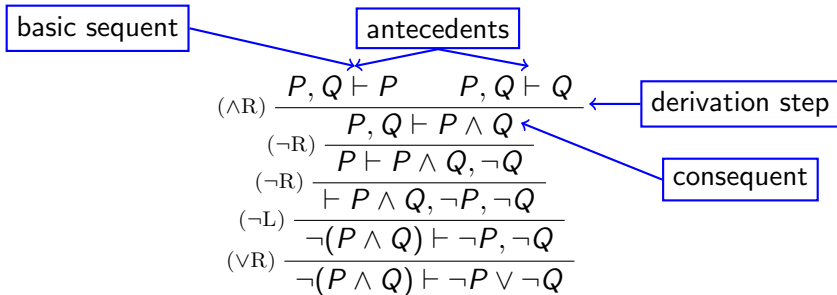
basic sequent

antecedents

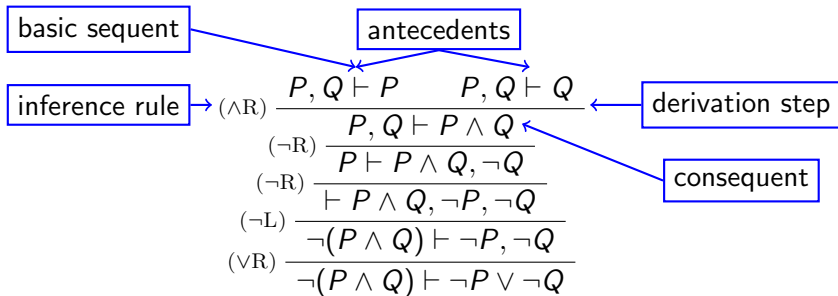
$$\begin{array}{c} (\wedge R) \frac{P, Q \vdash P \quad P, Q \vdash Q}{P, Q \vdash P \wedge Q} \\ (\neg R) \frac{P, Q \vdash P \wedge Q}{P \vdash P \wedge Q, \neg Q} \\ (\neg R) \frac{P \vdash P \wedge Q, \neg Q}{\vdash P \wedge Q, \neg P, \neg Q} \\ (\neg L) \frac{\vdash P \wedge Q, \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P, \neg Q} \\ (\vee R) \frac{\neg(P \wedge Q) \vdash \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P \vee \neg Q} \end{array}$$

derivation step

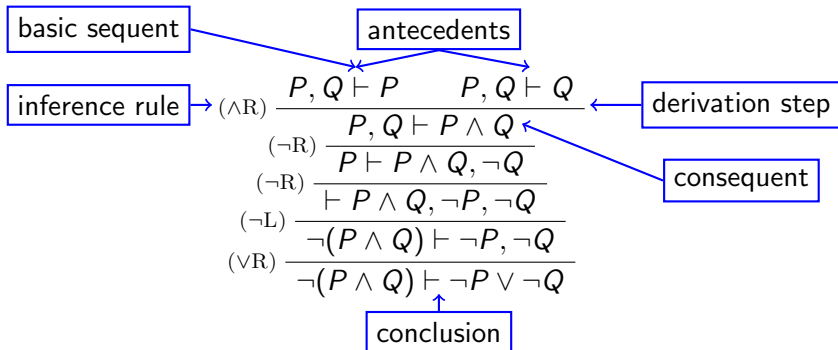
Example Derivation



Example Derivation



Example Derivation



Example Derivation (ctd.)

$\neg(P \wedge Q) \vdash \neg P \vee \neg Q$

$$(\neg\text{L}) \frac{\Gamma \vdash \varphi, \Delta}{\Gamma, \neg\varphi \vdash \Delta} \quad (\neg\text{R}) \frac{\Gamma, \varphi \vdash \Delta}{\Gamma \vdash \neg\varphi, \Delta}$$

$$(\wedge\text{R}) \frac{\Gamma \vdash \varphi, \Delta \quad \Gamma \vdash \psi, \Delta}{\Gamma \vdash \varphi \wedge \psi, \Delta}$$

$$(\vee\text{R}) \frac{\Gamma \vdash \varphi, \psi, \Delta}{\Gamma \vdash \varphi \vee \psi, \Delta}$$

Example Derivation (ctd.)

$$(\vee R) \frac{\neg(P \wedge Q) \vdash \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P \vee \neg Q}$$

$$(\neg L) \frac{\Gamma \vdash \varphi, \Delta}{\Gamma, \neg \varphi \vdash \Delta} \quad (\neg R) \frac{\Gamma, \varphi \vdash \Delta}{\Gamma \vdash \neg \varphi, \Delta}$$

$$(\wedge R) \frac{\Gamma \vdash \varphi, \Delta \quad \Gamma \vdash \psi, \Delta}{\Gamma \vdash \varphi \wedge \psi, \Delta}$$

$$(\vee R) \frac{\Gamma \vdash \varphi, \psi, \Delta}{\Gamma \vdash \varphi \vee \psi, \Delta}$$

Example Derivation (ctd.)

$$\begin{array}{l} (\neg\text{L}) \frac{\vdash P \wedge Q, \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P, \neg Q} \\ (\vee\text{R}) \frac{\neg(P \wedge Q) \vdash \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P \vee \neg Q} \end{array}$$

$$(\neg\text{L}) \frac{\Gamma \vdash \varphi, \Delta}{\Gamma, \neg\varphi \vdash \Delta} \quad (\neg\text{R}) \frac{\Gamma, \varphi \vdash \Delta}{\Gamma \vdash \neg\varphi, \Delta}$$

$$(\wedge\text{R}) \frac{\Gamma \vdash \varphi, \Delta \quad \Gamma \vdash \psi, \Delta}{\Gamma \vdash \varphi \wedge \psi, \Delta}$$

$$(\vee\text{R}) \frac{\Gamma \vdash \varphi, \psi, \Delta}{\Gamma \vdash \varphi \vee \psi, \Delta}$$

Example Derivation (ctd.)

$$\begin{array}{c} (\neg R) \frac{P \vdash P \wedge Q, \neg Q}{\vdash P \wedge Q, \neg P, \neg Q} \\ (\neg L) \frac{\vdash P \wedge Q, \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P, \neg Q} \\ (\vee R) \frac{\neg(P \wedge Q) \vdash \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P \vee \neg Q} \end{array}$$

$$(\neg L) \frac{\Gamma \vdash \varphi, \Delta}{\Gamma, \neg \varphi \vdash \Delta} \quad (\neg R) \frac{\Gamma, \varphi \vdash \Delta}{\Gamma \vdash \neg \varphi, \Delta}$$

$$(\wedge R) \frac{\Gamma \vdash \varphi, \Delta \quad \Gamma \vdash \psi, \Delta}{\Gamma \vdash \varphi \wedge \psi, \Delta}$$

$$(\vee R) \frac{\Gamma \vdash \varphi, \psi, \Delta}{\Gamma \vdash \varphi \vee \psi, \Delta}$$

Example Derivation (ctd.)

$$\begin{array}{c} (\neg R) \frac{P, Q \vdash P \wedge Q}{P \vdash P \wedge Q, \neg Q} \\ (\neg R) \frac{P \vdash P \wedge Q, \neg Q}{\vdash P \wedge Q, \neg P, \neg Q} \\ (\neg L) \frac{\vdash P \wedge Q, \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P, \neg Q} \\ (\vee R) \frac{\neg(P \wedge Q) \vdash \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P \vee \neg Q} \end{array}$$

$$(\neg L) \frac{\Gamma \vdash \varphi, \Delta}{\Gamma, \neg \varphi \vdash \Delta} \quad (\neg R) \frac{\Gamma, \varphi \vdash \Delta}{\Gamma \vdash \neg \varphi, \Delta}$$

$$(\wedge R) \frac{\Gamma \vdash \varphi, \Delta \quad \Gamma \vdash \psi, \Delta}{\Gamma \vdash \varphi \wedge \psi, \Delta}$$

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Example Derivation (ctd.)

$$\begin{array}{l} (\wedge R) \frac{P, Q \vdash P \quad P, Q \vdash Q}{P, Q \vdash P \wedge Q} \\ (\neg R) \frac{P \vdash P \wedge Q, \neg Q}{P \vdash P \wedge Q, \neg Q} \\ (\neg R) \frac{P \vdash P \wedge Q, \neg Q}{\vdash P \wedge Q, \neg P, \neg Q} \\ (\neg L) \frac{\vdash P \wedge Q, \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P, \neg Q} \\ (\vee R) \frac{\neg(P \wedge Q) \vdash \neg P, \neg Q}{\neg(P \wedge Q) \vdash \neg P \vee \neg Q} \end{array}$$

$$\begin{array}{l} (\neg L) \frac{\Gamma \vdash \varphi, \Delta}{\Gamma, \neg \varphi \vdash \Delta} \quad (\neg R) \frac{\Gamma, \varphi \vdash \Delta}{\Gamma \vdash \neg \varphi, \Delta} \\ (\wedge R) \frac{\Gamma \vdash \varphi, \Delta \quad \Gamma \vdash \psi, \Delta}{\Gamma \vdash \varphi \wedge \psi, \Delta} \\ (\vee R) \frac{\Gamma \vdash \varphi, \psi, \Delta}{\Gamma \vdash \varphi \vee \psi, \Delta} \end{array}$$

Inference Rules for the Propositional Connectives

Basic sequents: $\Gamma, \varphi \vdash \varphi, \Delta$
 $\Gamma, \perp \vdash \Delta$

$$(\neg L) \frac{\Gamma \vdash \varphi, \Delta}{\Gamma, \neg \varphi \vdash \Delta}$$

$$(\wedge L) \frac{\Gamma, \varphi, \psi \vdash \Delta}{\Gamma, \varphi \wedge \psi \vdash \Delta}$$

$$(\vee L) \frac{\Gamma, \varphi \vdash \Delta \quad \Gamma, \psi \vdash \Delta}{\Gamma, \varphi \vee \psi \vdash \Delta}$$

$$(\rightarrow L) \frac{\Gamma \vdash \varphi, \Delta \quad \Gamma, \psi \vdash \Delta}{\Gamma, \varphi \rightarrow \psi \vdash \Delta}$$

$$(\text{CUT}) \frac{\Gamma \vdash \varphi, \Delta \quad \Gamma, \varphi \vdash \Delta}{\Gamma \vdash \Delta}$$

$$(\neg R) \frac{\Gamma, \varphi \vdash \Delta}{\Gamma \vdash \neg \varphi, \Delta}$$

$$(\wedge R) \frac{\Gamma \vdash \varphi, \Delta \quad \Gamma \vdash \psi, \Delta}{\Gamma \vdash \varphi \wedge \psi, \Delta}$$

$$(\vee R) \frac{\Gamma \vdash \varphi, \psi, \Delta}{\Gamma \vdash \varphi \vee \psi, \Delta}$$

$$(\rightarrow R) \frac{\Gamma, \varphi \vdash \psi, \Delta}{\Gamma \vdash \varphi \rightarrow \psi, \Delta}$$

Example Derivations

$$\vdash ((P \rightarrow Q) \rightarrow P) \rightarrow P$$

Example Derivations

$$(\rightarrow R) \frac{(P \rightarrow Q) \rightarrow P \vdash P}{\vdash ((P \rightarrow Q) \rightarrow P) \rightarrow P}$$

Example Derivations

$$\begin{array}{c} (\rightarrow\text{L}) \frac{\vdash P \rightarrow Q, P \quad P \vdash P}{(P \rightarrow Q) \rightarrow P \vdash P} \\ (\rightarrow\text{R}) \frac{}{\vdash ((P \rightarrow Q) \rightarrow P) \rightarrow P} \end{array}$$

Example Derivations

$$\begin{array}{c} (\rightarrow R) \frac{P \vdash Q, P}{\vdash P \rightarrow Q, P} \quad P \vdash P \\ (\rightarrow L) \frac{\vdash P \rightarrow Q, P \quad P \vdash P}{(P \rightarrow Q) \rightarrow P \vdash P} \\ (\rightarrow R) \frac{(P \rightarrow Q) \rightarrow P \vdash P}{\vdash ((P \rightarrow Q) \rightarrow P) \rightarrow P} \end{array}$$

Example Derivations (ctd.)

$$\neg\neg P \vdash P$$

Example Derivations (ctd.)

$$(\neg\text{L}) \frac{\vdash \neg P, P}{\neg\neg P \vdash P}$$

Example Derivations (ctd.)

$$\begin{array}{l} (\neg R) \frac{P \vdash P}{\vdash \neg P, P} \\ (\neg L) \frac{}{\neg \neg P \vdash P} \end{array}$$

Example Derivations (ctd.)

$$P \vee \perp \vdash P$$

Example Derivations (ctd.)

$$(\vee L) \frac{P \vdash P \quad \perp \vdash P}{P \vee \perp \vdash P}$$

Inference Rules for the Quantifiers

$$(\forall L) \frac{\Gamma, \varphi[t/x] \vdash \Delta}{\Gamma, \forall x. \varphi \vdash \Delta}$$

$$(\forall R) \frac{\Gamma \vdash \varphi, \Delta}{\Gamma \vdash \forall x. \varphi, \Delta} \text{ if } x \notin \text{FV}(\Gamma, \Delta)$$

$$(\exists L) \frac{\Gamma, \varphi \vdash \Delta}{\Gamma, \exists x. \varphi \vdash \Delta} \text{ if } x \notin \text{FV}(\Gamma, \Delta)$$

$$(\exists R) \frac{\Gamma \vdash \varphi[t/x], \Delta}{\Gamma \vdash \exists x. \varphi, \Delta}$$

Example Derivations

$$\forall x.P(x) \wedge Q(x) \vdash (\forall x.P(x)) \wedge (\forall x.Q(x))$$

Example Derivations

$$(\wedge R) \frac{\forall x.P(x) \wedge Q(x) \vdash \forall x.P(x) \quad \forall x.P(x) \wedge Q(x) \vdash \forall x.Q(x)}{\forall x.P(x) \wedge Q(x) \vdash (\forall x.P(x)) \wedge (\forall x.Q(x))}$$

Example Derivations

$$\begin{array}{c} (\forall R) \frac{\forall x.P(x) \wedge Q(x) \vdash P(x)}{\forall x.P(x) \wedge Q(x) \vdash \forall x.P(x)} \quad \forall x.P(x) \wedge Q(x) \vdash \forall x.Q(x) \\ (\wedge R) \frac{\quad}{\forall x.P(x) \wedge Q(x) \vdash (\forall x.P(x)) \wedge (\forall x.Q(x))} \end{array}$$

Example Derivations

$$\begin{array}{l} \text{(\forall L)} \frac{P(x) \wedge Q(x) \vdash P(x)}{\forall x.P(x) \wedge Q(x) \vdash P(x)} \\ \text{(\forall R)} \frac{}{\forall x.P(x) \wedge Q(x) \vdash \forall x.P(x)} \quad \forall x.P(x) \wedge Q(x) \vdash \forall x.Q(x) \\ \text{(\wedge R)} \frac{}{\forall x.P(x) \wedge Q(x) \vdash (\forall x.P(x)) \wedge (\forall x.Q(x))} \end{array}$$

Example Derivations

$$\begin{array}{l} (\wedge L) \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)} \\ (\forall L) \frac{(\wedge L) \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)}}{\forall x.P(x) \wedge Q(x) \vdash P(x)} \\ (\forall R) \frac{(\forall L) \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)}}{\forall x.P(x) \wedge Q(x) \vdash \forall x.P(x)} \quad \forall x.P(x) \wedge Q(x) \vdash \forall x.Q(x) \\ (\wedge R) \frac{(\forall R) \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)} \quad \forall x.P(x) \wedge Q(x) \vdash \forall x.Q(x)}{\forall x.P(x) \wedge Q(x) \vdash (\forall x.P(x)) \wedge (\forall x.Q(x))} \end{array}$$

Example Derivations

$$\begin{array}{c} (\wedge L) \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)} \\ (\forall L) \frac{P(x) \wedge Q(x) \vdash P(x)}{\forall x. P(x) \wedge Q(x) \vdash P(x)} \\ (\forall R) \frac{\forall x. P(x) \wedge Q(x) \vdash \forall x. P(x)}{\forall x. P(x) \wedge Q(x) \vdash \forall x. P(x)} \\ (\wedge R) \frac{\forall x. P(x) \wedge Q(x) \vdash \forall x. P(x) \quad \forall x. P(x) \wedge Q(x) \vdash \forall x. Q(x)}{\forall x. P(x) \wedge Q(x) \vdash (\forall x. P(x)) \wedge (\forall x. Q(x))} \end{array}$$

Example Derivations

$$\begin{array}{c} (\wedge L) \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)} \\ (\forall L) \frac{P(x) \wedge Q(x) \vdash P(x)}{\forall x.P(x) \wedge Q(x) \vdash P(x)} \\ (\forall R) \frac{\forall x.P(x) \wedge Q(x) \vdash \forall x.P(x)}{\forall x.P(x) \wedge Q(x) \vdash \forall x.P(x)} \\ (\wedge R) \frac{\forall x.P(x) \wedge Q(x) \vdash \forall x.P(x)}{\forall x.P(x) \wedge Q(x) \vdash (\forall x.P(x)) \wedge (\forall x.Q(x))} \end{array} \quad \begin{array}{c} (\forall L) \frac{P(x) \wedge Q(x) \vdash Q(x)}{\forall x.P(x) \wedge Q(x) \vdash Q(x)} \\ (\forall R) \frac{\forall x.P(x) \wedge Q(x) \vdash \forall x.Q(x)}{\forall x.P(x) \wedge Q(x) \vdash \forall x.Q(x)} \end{array}$$

Example Derivations

$$\begin{array}{c} \text{(\wedge L)} \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)} \\ \text{(\forall L)} \frac{\text{(\wedge L)} \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)}}{\forall x.P(x) \wedge Q(x) \vdash P(x)} \\ \text{(\forall R)} \frac{\text{(\forall L)} \frac{\text{(\wedge L)} \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)}}{\forall x.P(x) \wedge Q(x) \vdash P(x)}}{\forall x.P(x) \wedge Q(x) \vdash \forall x.P(x)} \\ \text{(\wedge R)} \frac{\text{(\forall R)} \frac{\text{(\forall L)} \frac{\text{(\wedge L)} \frac{P(x), Q(x) \vdash P(x)}{P(x) \wedge Q(x) \vdash P(x)}}{\forall x.P(x) \wedge Q(x) \vdash P(x)}}{\forall x.P(x) \wedge Q(x) \vdash \forall x.P(x)}}{\forall x.P(x) \wedge Q(x) \vdash (\forall x.P(x)) \wedge (\forall x.Q(x))} \end{array} \quad \begin{array}{c} \text{(\wedge L)} \frac{P(x), Q(x) \vdash Q(x)}{P(x) \wedge Q(x) \vdash Q(x)} \\ \text{(\forall L)} \frac{\text{(\wedge L)} \frac{P(x), Q(x) \vdash Q(x)}{P(x) \wedge Q(x) \vdash Q(x)}}{\forall x.P(x) \wedge Q(x) \vdash Q(x)} \\ \text{(\forall R)} \frac{\text{(\forall L)} \frac{\text{(\wedge L)} \frac{P(x), Q(x) \vdash Q(x)}{P(x) \wedge Q(x) \vdash Q(x)}}{\forall x.P(x) \wedge Q(x) \vdash Q(x)}}{\forall x.P(x) \wedge Q(x) \vdash \forall x.Q(x)} \\ \text{(\wedge R)} \frac{\text{(\forall R)} \frac{\text{(\forall L)} \frac{\text{(\wedge L)} \frac{P(x), Q(x) \vdash Q(x)}{P(x) \wedge Q(x) \vdash Q(x)}}{\forall x.P(x) \wedge Q(x) \vdash Q(x)}}{\forall x.P(x) \wedge Q(x) \vdash \forall x.Q(x)}}{\forall x.P(x) \wedge Q(x) \vdash (\forall x.P(x)) \wedge (\forall x.Q(x))} \end{array}$$

Example Derivations (ctd.)

The following derivation violates a side condition:

$$\begin{array}{c} (\exists\text{L}) \frac{P(x) \vdash P(x)}{\exists x.P(x) \vdash P(x)} \\ (\forall\text{R}) \frac{\exists x.P(x) \vdash P(x)}{\exists x.P(x) \vdash \forall x.P(x)} \\ (\rightarrow\text{R}) \frac{\exists x.P(x) \vdash \forall x.P(x)}{\vdash (\exists x.P(x)) \rightarrow (\forall x.P(x))} \end{array}$$

Inference Rules for Equality

$$\text{Basic sequent: } \Gamma \vdash t \doteq t, \Delta \quad (\text{SUBST}) \frac{s \doteq t, \Gamma[s/x] \vdash \Delta[s/x]}{s \doteq t, \Gamma[t/x] \vdash \Delta[t/x]}$$

$$s \doteq t \vdash t \doteq s$$

Inference Rules for Equality

$$\text{Basic sequent: } \Gamma \vdash t \doteq t, \Delta \quad (\text{SUBST}) \frac{s \doteq t, \Gamma[s/x] \vdash \Delta[s/x]}{s \doteq t, \Gamma[t/x] \vdash \Delta[t/x]}$$

$$s \doteq t \vdash \underbrace{t \doteq s}_{\equiv (x \doteq s)[t/x]}$$

Inference Rules for Equality

Basic sequent: $\Gamma \vdash t \doteq t, \Delta$

$$(\text{SUBST}) \frac{s \doteq t, \Gamma[s/x] \vdash \Delta[s/x]}{s \doteq t, \Gamma[t/x] \vdash \Delta[t/x]}$$

$$(\text{SUBST}) \frac{s \doteq t \vdash \overbrace{s \doteq s}^{\equiv (x \doteq s)[s/x]}}{s \doteq t \vdash \underbrace{t \doteq s}_{\equiv (x \doteq s)[t/x]}}$$

Soundness and Completeness

We write $\Gamma \vdash_{\text{LK}} \Delta$ to mean that there is a derivation of $\Gamma \vdash \Delta$.

Theorem 15 (Soundness of LK)

The system LK is sound: If $\Gamma \vdash_{\text{LK}} \varphi$ then $\Gamma \models \varphi$.

Theorem 16 (Consistency of LK)

The system LK is consistent: There is a formula φ such that $\not\vdash_{\text{LK}} \varphi$.

Theorem 17 (Completeness of LK)

The system LK is complete: If $\Gamma \models \varphi$ then $\Gamma \vdash_{\text{LK}} \varphi$.